

INVESTIGATION OF THE STABILITY OF THE SOLUTIONS
OF A LINEAR DIFFERENTIAL EQUATION WITH PERIODIC
COEFFICIENTS AND WITH STATIONARY DELAYS
IN THE ARGUMENT BY THE METHOD OF HILL

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In this article it is shown that Hill's method [1] can be applied to the investigation of the solutions of a linear differential equation with periodic coefficients and with stationary lags in the argument. The presentation is made with the aid of a second order differential equation with concentrated lags. The presented method can be extended quite easily to systems of n equations of the n th order with concentrated and uniformly distributed stationary lags in the argument.

1. The following equation is considered

$$\frac{d^2 y(t)}{dt^2} + \sum_{k=0}^s \sum_{q=-l}^l a_{kq} e^{-iqt} y(t - \tau_k) = 0 \quad (1.1)$$

Here the a_{kq} are complex numbers, the τ_k are real numbers such that

$$0 = \tau_0 < \tau_1 < \dots < \tau_s \leq h,$$

and l is a positive number. The problem is to find, for positive t , a solution $y(t)$ that satisfies the initial conditions

$$y(t) = \varphi(t) \quad (h \leq t < 0), \quad y(0) = y_0^{(0)}, \quad \frac{dy}{dt}(0) = y_0^{(1)} \quad (1.2)$$

The function $\varphi(t)$ is absolutely integrable over $h \leq t < 0$.

Let $f(p)$ be the Laplace transform [2] of the desired solution of Equation (1.1) satisfying the initial conditions (1.2).

Multiplying (1.1) by e^{-pt} and integrating with respect to t between the limits 0 and $+\infty$, we obtain the difference equation for the determination of $f(p)$:

$$p^2 f(p) + \sum_{q=-l}^l b_q(p+qi) f(p+qi) = \psi(p) \tag{1.3}$$

Here

$$b_q(p) = \sum_{k=0}^s a_{kq} e^{-\tau_k p}, \quad \psi(p) = p y_0^{(0)} + y_0^{(1)} - \sum_{q=-l}^l \Psi_q(p+qi) \tag{1.4}$$

$$\Psi_q(p) = \sum_{k=1}^s a_{kq} \int_{-\tau_k}^0 \psi(\tau) e^{-p(\tau+\tau_k)} d\tau \tag{1.5}$$

The functions $b_q(p)$ in (1.4) are bounded in the half-plane $\text{Re } p \geq c = \text{const}$. Replacing p in (1.3) by $(p + ki)$ and dividing the obtained difference equation by $-k^2$ ($k = \pm 1, \pm 2, \pm 3, \dots$), we obtain an infinite system of linear algebraic equations in the unknowns $f(p + ki)$:

$$-k^2 f(p + ki) - \sum_{q=-l}^l k^{-2} b_q(p + (k+q)i) f(p + (k+q)i) = -k^{-2} \psi(p + ki) \tag{1.6}$$

$(k = \pm 1, \pm 2, \pm 3, \dots)$

The complex variable p in (1.6) and (1.3) will be treated as a parameter. Solving the system of Equations (1.3) and (1.6) by means of Cramer's formula, we obtain

$$f(p) = \frac{1}{\Delta(p)} \begin{vmatrix} \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & -[(p+i)^2 + b_0(p+i)] & -\psi(p+i) & -b_{-2}(p-i) & \dots & \dots \\ \dots & b_1(p+i) & \psi(p) & b_{-1}(p-i) & \dots & \dots \\ \dots & -b_2(p+i) & -\psi(p-i) & -[(p-i)^2 + b_0(p-i)] & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{vmatrix} \tag{1.7}$$

Here, $\Delta(p)$ denotes the infinite determinant of the system (1.3), (1.6).

$$\Delta(p) = \begin{vmatrix} \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & -[(p+i)^2 + b_0(p+i)] & -b_{-1}(p) & -b_{-2}(p-i) & \dots & \dots \\ \dots & b_1(p+i) & p^2 + b_0(p) & b_{-1}(p-i) & \dots & \dots \\ \dots & -b_2(p+i) & -b_1(p) & -[(p-i)^2 + b_0(p-i)] & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{vmatrix} \tag{1.8}$$

One can show that the determinant $\Delta(p)$ in (1.8) converges absolutely and uniformly [3] in every bounded region Σ of the complex plane p . The product of the diagonal elements $A(p)$ of the determinant $\Delta(p)$ can be represented in the form

It is obvious that the determinant $D(p)$ is periodic of period i .

Hence, we have proved the following theorem.

Theorem 2.1. Hill's determinant $\Delta(p)$ in (1.8), constructed for the differential equation (1.1) with periodic coefficients and stationary lag of the argument, is an entire periodic function of p with period i .

From (2.5), (2.3) and (1.4) it follows that $D(p) \rightarrow 1$ when $\text{Re } p \rightarrow +\infty$. Since $b_0(p) \rightarrow a_{00}$ in (1.4) when $\text{Re } p \rightarrow +\infty$, we obtain, by retaining the term with largest absolute value, the asymptotic expression for $A(p)$ of (1.9) when $\text{Re } p \rightarrow +\infty$,

$$A(p) \sim (p^2 + a_{00}) \prod_{\substack{k=-\infty \\ k \neq 0}}^{\infty} [-k^{-2} ((p + ki)^2 + a_{00})] = \frac{1}{2\pi^2} (\cosh 2\pi p - \cosh 2\pi \sqrt{-a_{00}}) \sim \frac{e^{2\pi p}}{4\pi^2} \quad (2.6)$$

In the particular case when the lags τ_k in (1.1) are multiples of 2π , the function $b_0(p)$ in (1.4) will be periodic with period i , and we obtain, when $\text{Re } p \rightarrow +\infty$, the equation

$$A(p) = \frac{1}{2\pi^2} \left[\cosh 2\pi p - \cosh 2\pi \left(-\sum_{k=0}^s a_{k0} \exp\{-\tau_k p\} \right)^{\frac{1}{2}} \right] = \frac{e^{2\pi p}}{4\pi^2} + O(1) \quad (2.7)$$

Let us make the following substitution in (1.8)

$$\rho = \exp\{-2\pi p\} \quad (2.8)$$

Because of the periodicity of the determinant $\Delta(p)$, the function

$$\Phi(\rho) = \rho \Delta \left(-\frac{1}{2\pi} \ln \rho \right) 4\pi^2 = 1 + O(\rho), \quad \rho \rightarrow 0 \quad (2.9)$$

is a single-valued function without finite poles, namely, it is an entire function of ρ . By Weierstrass' theorem [2, p. 407] we have

$$\Phi(\rho) = \exp(g(\rho)) \prod_{n=1}^{\infty} \left(1 - \frac{\rho}{\rho_n} \right) \exp \left\{ \frac{\rho}{\rho_n} + \frac{1}{2} \frac{\rho^2}{\rho_n^2} + \dots + \frac{1}{k_n} \left(\frac{\rho}{\rho_n} \right)^{k_n} \right\} \quad (2.10)$$

Here $g(\rho)$ is an entire function of ρ , $g(0) = 0$, the ρ_n are the zeros of $\Phi(\rho)$ when $n \rightarrow \infty$, and the k_n are certain integers which will guarantee the convergence of (2.10). Making use of the notation $p_j = -0.5 \pi^{-1} \ln \rho_j$, we obtain from (2.10) and (2.9) the general form of the analytic representation of $\Delta(p)$ in (1.8):

$$\Delta(p) = 0,25\pi^{-2} \exp(2\pi p) \exp[g(\exp\{-2\pi p\})] \times \prod_{n=1}^{\infty} \{ 1 - \exp\{2\pi(p_j - p)\} \} \exp\{2\pi(p_j - p)\} + \dots + \frac{1}{k_n} \exp\{2\pi k_n(p_j - p)\} \} \quad (2.11)$$

$$g(p) = g_1 p + g_2 p^2 + g_3 p^3 + \dots + \lim_{n \rightarrow \infty} \sqrt[n]{|g_n|} = 0, \quad \operatorname{Re} p_n \rightarrow -\infty \text{ when } n \rightarrow \infty \quad (2.12)$$

The determination of the behavior of the numbers p_n and g_n when $n \rightarrow \infty$ is still an unsolved problem.

3. The problem of the stability of the solutions of Equation (1.1) involves the evaluation of the characteristic exponents p_n of the solution of Equation (1.1). From theorem 2.1 it follows that the transform $f(p)$ (1.7) of the solution $y(t)$ is a meromorphic function of p with poles at the points

$$p_{nk} = p_n + ki \quad (n = 1, 2, \dots, k = 0, \pm 1, \pm 2, \dots) \quad (3.1)$$

If we seek the original function $y(t)$ with the aid of the expansion given on p. 483 of [2], we obtain the next theorem.

Theorem 3.1. The solution $y(t)$ of Equation (1.1) with the initial conditions (1.2) can always be expanded into a series of the type

$$y(t) = \sum_{n=1}^{\infty} y_n(t), \quad y_n(t) = \sum_{k=-\infty}^{\infty} (\beta_{nk}^{(0)} + \beta_{nk}^{(1)} t + \dots + \beta_{nk}^{(r_n)} t^{r_n}) e^{(p_n + ki)t} \quad (3.2)$$

where $r_n + 1$ is the multiplicity of the zero p_n of the determinant $\Delta(p)$ (1.8).

If we substitute $y_n(t)$ from (3.2) into (1.1) we find that $y_n(t)$ is indeed a solution of Equation (1.1).

The equations for $\beta_{nk}^{(r)}$ will be satisfied because Equations (1.3) and (1.5) are satisfied by $f(p)$ which has poles of order $r_n + 1$ at the points p_{nk} (3.1).

Hence, $y_n(t)$ is an entire function of t , and the series for $y_n(t)$ (3.2) converges absolutely and uniformly for all finite values of t . This implies the asymptotic nature of the series (3.2). Thus we obtain the next theorem.

Theorem 3.2. The solution $y(t)$ of Equation (1.1) with the conditions (1.2) can always be expanded into an asymptotic series, with $t \rightarrow \infty$, of the form

$$y(t) = \sum_{n=1}^{\infty} e^{p_n t} (\alpha_n^{(0)}(t) + \alpha_n^{(1)}(t) t + \dots + \alpha_n^{(r_n)}(t) t^{r_n}) \quad (3.3)$$

Here $\alpha_n^{(r)}(t + 2\pi) \equiv \alpha_n^{(r)}(t)$, $\operatorname{Re} p_n \rightarrow -\infty$ when $n \rightarrow +\infty$, and $r_n + 1$ stands for the multiplicity of the zero p_n of the determinant $\Delta(p)$ (1.8).

We may assume, without loss of generality, that $\operatorname{Re} p_1 > \operatorname{Re} p_2 > \operatorname{Re} p_3 > \dots$. Then we have the following result if $\operatorname{Re} p^* < \operatorname{Re} p_{k+1}$:

$$\lim_{t \rightarrow \infty} \left| y(t) - \sum_{n=1}^k y_n(t) \right| \exp \{p^* t\} = 0 \quad (3.4)$$

Theorem 3.2 permits us to draw certain conclusions about the stability of the solutions of Equation (1.1) if we know the zeros p_n of the determinant Δp . This theorem can be extended to systems of linear differential equations with periodic coefficients and with stationary lags of the argument, see for example [3]. In order to find the characteristic exponents p_n , one can make use of the conditions for the existence of the solution $y(t)$ of Equation (1.1) in the form

$$y(t) = e^{pt} \sum_{k=-\infty}^{\infty} \beta_k e^{ikt} \quad (3.5)$$

4. We shall consider the Mathieu equation

$$\frac{d^2 y(t)}{dt^2} + \lambda y(t) + 2\mu y(t - \tau) \cos 2t = 0 \quad (4.1)$$

Here λ , $\mu \geq 0$, and $\tau \geq 0$ are real parameters. Equation (1.3) takes on the form

$$(p^2 + \lambda) f(p) + \mu e^{-(p+2i)\tau} f(p+2i) + \mu e^{-(p-2i)\tau} f(p-2i) = \psi(p) \quad (4.2)$$

The solution of a difference equation of the type (4.2) is given in [4, p.983].

From the determinant $\Delta(p)$ one can obtain the equation [4]

$$f_0(p) - s(p) - h(p) = 0 \quad (4.3)$$

where the notation of [4, p.984] is used:

$$f_0(p) = p^2 + \lambda, \quad f_1(p) = f_{-1}(p) = \mu e^{-p\tau}, \quad \omega = 2i \quad (4.4)$$

$$s(p) = \frac{f_1(p+\omega) f_{-1}(p)}{f_0(p+\omega) - \frac{f_1(p+2\omega) f_{-1}(p+\omega)}{f_0(p+2\omega) - \dots}}, \quad h(p) = \frac{f_{-1}(p-\omega) f_1(p)}{f_0(p+\omega) - \frac{f_{-1}(p-2\omega) f_1(p-\omega)}{f_0(p-2\omega) - \dots}} \quad (4.5)$$

For Equation (4.1) with $\lambda \neq k^2$ ($k = 0, 1, 2, \dots$) Equation (4.3) takes on the form

$$p^2 + \lambda - \frac{\mu^2 e^{-2\tau(p+i)}}{(p+2i)^2 + \lambda} - \frac{\mu^2 e^{-2\tau(p-i)}}{(p-2i)^2 + \lambda} + O(\mu^4) = 0 \quad (4.6)$$

From Equation (4.6) we find the characteristic exponent p , which is near $i\sqrt{\lambda}$ for small values of μ

$$p = i\sqrt{\lambda} + i \frac{\mu^2}{4\sqrt{\lambda}(1-\lambda)} (\cos 2\tau \sqrt{\lambda} \cos 2\tau + \sqrt{\lambda} \sin 2\tau \sin 2\tau \sqrt{\lambda}) + \\ + \frac{\mu^2}{4\sqrt{\lambda}(1-\lambda)} (\sin 2\tau \sqrt{\lambda} \cos 2\tau - \sqrt{\lambda} \cos 2\tau \sqrt{\lambda} \sin 2\tau) + O(\mu^4) \quad (4.7)$$

If the lag $\tau > 0$ is sufficiently small, then

$$\operatorname{Re} p = -\frac{2}{3} \mu^2 \tau^3 + O(|\mu^2 \tau^5| + |\mu^4|) \quad (4.8)$$

The solutions (4.1) will be asymptotically stable for small enough values $\mu > 0$, $\tau > 0$, and $\lambda \neq k^2$ ($k = 0, 1, 2, \dots$). Suppose that $\lambda = 0.25$. Then (4.7) yields

$$\operatorname{Re} p = -\frac{2}{3} \mu^2 \sin^3 \tau + O(\mu^4) \quad (4.9)$$

For large values of the lag $\tau > 0$, $(2n+1)\pi < \tau < (2n+2)\pi$ ($n = 0, 1, 2, \dots$), and for sufficiently small values of $\mu > 0$, the solutions of Equation (4.1) are unstable.

5. For the investigation of the resonance $\lambda = k^2$ ($k = 0, 1, 2, \dots$) in Equation (4.1), we shall make use of the following lemma.

Lemma 5.1. Let $\varphi(p, \mu)$ be a holomorphic function of μ and p when $|\mu| < \varepsilon$ and $|p| < \varepsilon$. Let us consider the equation

$$\varphi(p, \mu) \equiv a_0(\mu) + a_1(\mu)p + a_2(\mu)p^2 + a_3(\mu)p^3 + \dots = 0 \quad (5.1) \\ O(a_0) = O(\mu^2), \quad O(a_1) = (\mu), \quad O(a_n) = O(1) \quad (n = 2, 3, \dots), \quad a_2(\mu) > 0$$

If it is known that two of the smallest (in absolute value) roots p_1, p_2 of Equation (5.1) are conjugates of each other, then a necessary and sufficient condition for the negativeness of the $\operatorname{Re} p_1$ and $\operatorname{Re} p_2$ is given by

$$\varphi(0, \mu) = a_0(\mu) > 0 \quad (5.2)$$

$$a_1 - \frac{a_0 a_2 a_3^2}{a_2^3 - a_1 a_3} + \frac{a_0 a_2 a_4 (a_1 a_2 - a_0 a_3)}{(a_2^3 - a_1 a_3)^2} + O(\mu^4) > 0 \quad (5.3)$$

The proof of this lemma can be obtained from Weierstrass's theorem [5, p.9] by dividing $\varphi(p, \mu)$ of (5.1) by a factor, a quadratic function of p , and with the use of Hurwitz's condition [2, p.427].

Example 5.1. We shall determine the conditions for the stability of the solutions of Equation (4.1) when $\mu \approx 0$, $\lambda \approx 0$. Applying the Lemma 5.1 to Equation (4.6) and taking into account the terms of order less than $O(\mu^6 + \mu^4 |\lambda| + \lambda^2 \mu^2)$, we obtain the conditions for stability when

$|\mu|$ and $|\lambda|$ are small:

$$\lambda + 0.5\mu^2 \cos 2\tau + 0.125\mu^2\lambda \cos 2\tau + \frac{\mu^4}{128} \cos 8\tau > 0 \quad (5.4)$$

$$\begin{aligned} \mu^2 \left[\left(-\tau - \tau\lambda + \frac{2}{3} \tau^2\lambda \right) \cos 2\tau + \left(\frac{1}{2} + \frac{\lambda}{2} - \lambda\tau^2 \right) \sin 2\tau \right] + \mu^4 \left[\left(-\frac{\tau}{4} - \frac{\tau^3}{3} \right) + \right. \\ \left. + \left(\frac{\tau}{4} - \frac{\tau^3}{3} \right) \cos 4\tau + \left(-\frac{1}{32} + \frac{\tau^2}{2} \right) \sin 4\tau - \frac{\tau}{32} \cos 8\tau + \frac{5}{256} \sin 8\tau \right] > 0 \end{aligned} \quad (5.5)$$

When $\tau = 0$, the condition (5.4) reduces to Mathieu's criterion for stability. The Condition (5.5) is the second nonobvious criterion for stability. When $\tau > 0$ is small, the latter criterion takes on the form

$$\frac{4}{3} \mu^2 \tau^3 + O(|\mu^2 \tau^5| + |\mu^2 \lambda| + |\mu^4|) > 0 \quad (5.6)$$

Example 5.2. We shall find the conditions for stability of the solutions of Equation (4.1) when $|\lambda - 1|$, and $|\mu|$ are small.

Let us rewrite the condition (4.3) in a more convenient form ($2i = \omega$)

$$[f_0(p) - s(p)] [f_0(p - 2i) - h(p - 2i)] = f_{-1}(p - 2i) f_1(p) \quad (5.7)$$

After the substitution of (4.4) into Equation (5.7), the latter takes the form

$$\begin{aligned} \left[p^2 + \lambda - \frac{\mu^2 e^{-2\tau(p+i)}}{(p+2i)^2 + \lambda} - \frac{\mu^4 e^{-4\tau(p+2i)}}{[(p+2i)^2 + \lambda]^2 [(p+4i)^2 + \lambda]} + O(\mu^6) \right] \left[(p-2i)^2 + \lambda - \right. \\ \left. - \frac{\mu^2 e^{-2\tau(p-3i)}}{(p-4i)^2 + \lambda} - \frac{\mu^4 e^{-4\tau(p+4i)}}{[(p-4i)^2 + \lambda]^2 [(p-6i)^2 + \lambda]} + O(\mu^6) \right] = \mu^2 e^{-2\tau(p-i)} \end{aligned} \quad (5.8)$$

Let us set $p = i + z$ in (5.8). Expanding (5.8) in powers of z , and making use of Lemma 5.1, we obtain the inequalities

$$\left(\lambda - 1 + \frac{\mu^2 \cos 4\tau}{9 - \lambda} + \frac{\mu^4 \cos 12\tau}{1536} \right)^2 + \frac{\mu^4 \sin^2 4\tau}{64} > \mu^2 + O(\mu^6 + \mu^4 |\lambda - 1|) \quad (5.9)$$

$$\frac{4}{3} \mu^2 \tau^3 + O(\mu^2 (\lambda - 1)^2 + \mu^2 \tau^5 + \mu^4) > 0 \quad (5.10)$$

Example 5.3. Let us investigate the stability of the Mathieu equation with lag and friction

$$\frac{d^2 y(t)}{dt^2} + \mu c \frac{dy(t)}{dt} + \lambda y(t) + 2\mu \cos 2t y(t - \tau) = 0, \quad c > 0 \quad (5.11)$$

when $|\lambda - 1|$, $|\mu|$ are sufficiently small. For the purpose of finding the characteristic exponents it is advisable to use (5.7), where one has to set

$$f_0(p) = p^2 + \mu c p + \lambda, \quad f_1(p) = f_{-1}(p) = \mu e^{-p\tau}, \quad \omega = 2i \quad (5.12)$$

Equation (5.7) now takes the form

$$\left[p^2 + \mu c p + \lambda - \frac{\lambda^2 e^{-2\tau(p+i)}}{(p+2i)^2 + \mu c(p+2i) + \lambda} + O(\mu^4) \right] \left[(p-2i)^2 + \mu c(p-2i) + \lambda - \frac{\mu^2 e^{-2\tau(p-3i)}}{(p+4i)^2 + \mu c(p+4i) + \lambda} + O(\mu^4) \right] = \mu^2 e^{-2\tau(p-i)} \quad (5.13)$$

Expanding Equation (5.13) in powers of $z = p - i$, and applying Lemma 5.1, we obtain the following conditions for stability:

$$\left(\lambda - 1 + \frac{\mu^2 \cos 4\tau}{8} \right)^2 + \mu^2 \left(c - \frac{\mu}{8} \sin 4\tau \right)^2 > \mu^2 + O(\mu^4 + \mu^3 |\lambda - 1|) \quad (5.14)$$

$$\mu c + \frac{4}{3} \mu^2 \tau^3 + O(\mu^3 + \mu^2 \tau^5 + \mu^2 (\lambda - 1)^2) > 0 \quad (5.15)$$

6. In the determination of the characteristic exponents it is convenient to transform the infinite determinant of Hill (1.8), (2.5) into a determinant of finite order, as is done in [6]. Let us consider the differential equation

$$\frac{d^2 y(t)}{dt^2} + \lambda y(t) + 2\mu \sum_{k=1}^{\infty} a_k \cos kty(t - \tau_k) = 0, \quad \sum_{k=1}^{\infty} |a_k| < \infty, \quad h < \tau_k \leq 0 \quad (6.1)$$

The difference equation for $f(p)$ (1.3) has the form

$$(p^2 + \lambda) f(p) + \mu \sum_{k=1}^{\infty} a_k (e^{-\tau_k(p+ki)} f(p+ki) + e^{-\tau_k(p-ki)} f(p-ki)) = \psi(p) \quad (6.2)$$

Suppose that $|\lambda| \ll 1$, $|\mu| \ll 1$. When $\mu = 0$, the poles of $f(p)$ are at $\pm \sqrt{-\lambda}$. Hence, one can look for the zeros of the determinant $\Delta(p)$ (1.8) in the region Σ

$$|\lambda| < \varepsilon, \quad |\mu| < \varepsilon, \quad |p| < \varepsilon \quad (6.3)$$

Let us transfer the diagonal element in each row of the determinant $\Delta(p)$ behind the symbol of the determinant, except for the one in the central row. For small $\varepsilon > 0$, the diagonal elements $-k^{-2}[(p+ki)^2 + \lambda]$ ($k \neq 0$) have no zeros in the region (6.3). Therefore, the remaining determinant $\text{Det } D_1(p)$ of the matrix $D_1(p)$ converges in the region (6.3). Hence we have

$$D_1(p) = \begin{vmatrix} \dots & \dots & \dots & \dots & \dots \\ \cdot & 1 & c_{-2}(p+i) & c_{-2}(p+i) & \cdot \\ \cdot & \mu a_1 \exp\{-\tau_1(p+i)\} & p^2 + \lambda & \mu a_1 \exp\{-\tau_1(p-i)\} & \cdot \\ \cdot & c_2(p-i) & c_1(p-i) & 1 & \cdot \\ \dots & \dots & \dots & \dots & \dots \end{vmatrix} \quad (6.4)$$

$$c_k(p) = \mu(p^2 + \lambda)^{-1} a_{|k|} \exp\{-\tau_k(p+ki)\} \quad (6.5)$$

When $\epsilon > 0$ is small, the zeros of the determinants $\Delta(p)$ (1.8) and $\text{Det } D_1(p)$ coincide in (6.3). Let us consider the auxiliary infinite matrix $R(p)$ with the determinant in (6.3) not equal to zero

$$R(p) = \begin{vmatrix} \dots & \dots & \dots & \dots & \dots \\ \cdot & 1 & c_{-1}(p+i) & c_{-2}(p+i) & \cdot \\ \cdot & 0 & 1 & 0 & \cdot \\ \cdot & c_2(p-i) & c_1(p-i) & 1 & \cdot \\ \dots & \dots & \dots & \dots & \dots \end{vmatrix} \quad \left. \begin{array}{l} \text{Det } R(p) \neq 0 \\ p \in \Sigma \end{array} \right\} \quad (6.6)$$

The matrix $R(p)$ coincides with the matrix $D_1(p)$ (6.4) except for the center row, where all the elements are replaced by zeros while the diagonal element is replaced by one.

Therefore, in the matrix $D_1(p) R^{-1}(p)$ there will be (except for the center row) ones along the diagonal and zeros off the diagonal. $\text{Det } (D_1(p) R^{-1}(p))$ reduces to a scalar function of p

$$\text{Det } (D_1(p) R^{-1}(p)) = \text{Det } D_1(p) \text{Det } R^{-1}(p), \quad \text{Det } R^{-1}(p) \neq 0 \quad p \in \Sigma \quad (6.7)$$

Let us find the matrix $(E + C(p))^{-1}$, where

$$E = \begin{vmatrix} \cdot & \cdot & \cdot & \cdot \\ \cdot & 1 & 0 & 0 \\ \cdot & 0 & 1 & 0 \\ \cdot & 0 & 0 & 1 \\ \cdot & \cdot & \cdot & \cdot \end{vmatrix} \quad C(p) = \begin{vmatrix} \cdot & \cdot & \cdot & \cdot \\ \cdot & 0 & c_{-1}(p+i) & c_{-2}(p+i) \\ \cdot & c_1(p) & 0 & c_{-1}(p) \\ \cdot & c_2(p-i) & c_1(p-i) & 0 \\ \cdot & \cdot & \cdot & \cdot \end{vmatrix} \quad (6.8)$$

$$(E + C(p))^{-1} = E - C(p) + C^2(p) - C^3(p) + \dots \quad (6.9)$$

If we eliminate from the matrix $(E + C(p))^{-1}$ the elements $c_k(p)$, which can have poles in the region Σ (6.3), then we obtain $R^{-1}(p)$, and the equation $\Delta(p) = 0$ takes on the form

$$p^2 + \lambda - \mu^2 \sum_{\substack{k=-\infty \\ k \neq 0}}^{\infty} \frac{a_k a_{-k} \exp[-\tau_k(p+ki) - \tau_{-k}p]}{(p+ki)^2 + \lambda} + \\ + \mu^3 \sum_{\substack{k, \alpha=-\infty \\ k, \alpha \neq 0}}^{\infty} \frac{a_k a_{\alpha-k} a_{-\alpha} \exp\{-\tau_k(p+ki) - \tau_{\alpha-k}(p+\alpha i) - \tau_{-\alpha}p\}}{[(p+(\alpha-k)i)^2 + \lambda][(p+\alpha i)^2 + \lambda]} - \dots = 0 \quad (6.10)$$

It is assumed here that $\tau_k = \tau_{-k}$, $a_k = a_{-k}$. In other cases, $\lambda = 0.25k^2$ ($k = 1, 2, \dots$), and one has to proceed in a similar manner but leave two rows unchanged, the center one and the k th one. Making use of Lemma 5.1, we obtain the condition for stability of the solutions of Equation (6.1) when $|\lambda|$ and $|\mu|$ are small:

$$\lambda + 2\mu^2 \sum_{k=1}^{\infty} \frac{a_k^2 \cos k\tau_k}{k^2 - \lambda} + O(\mu^3) > 0 \quad (6.11)$$

$$4\mu^4 \sum_{k=1}^{\infty} a_k^2 \left(\frac{\tau_k \cos k\tau_k}{\lambda - k^2} + \frac{k \sin k\tau_k}{(\lambda - k^2)^2} \right) + O(\mu^3 + \mu^2 |\lambda|) > 0 \quad (6.12)$$

The second of these conditions is not independent on the first one.

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